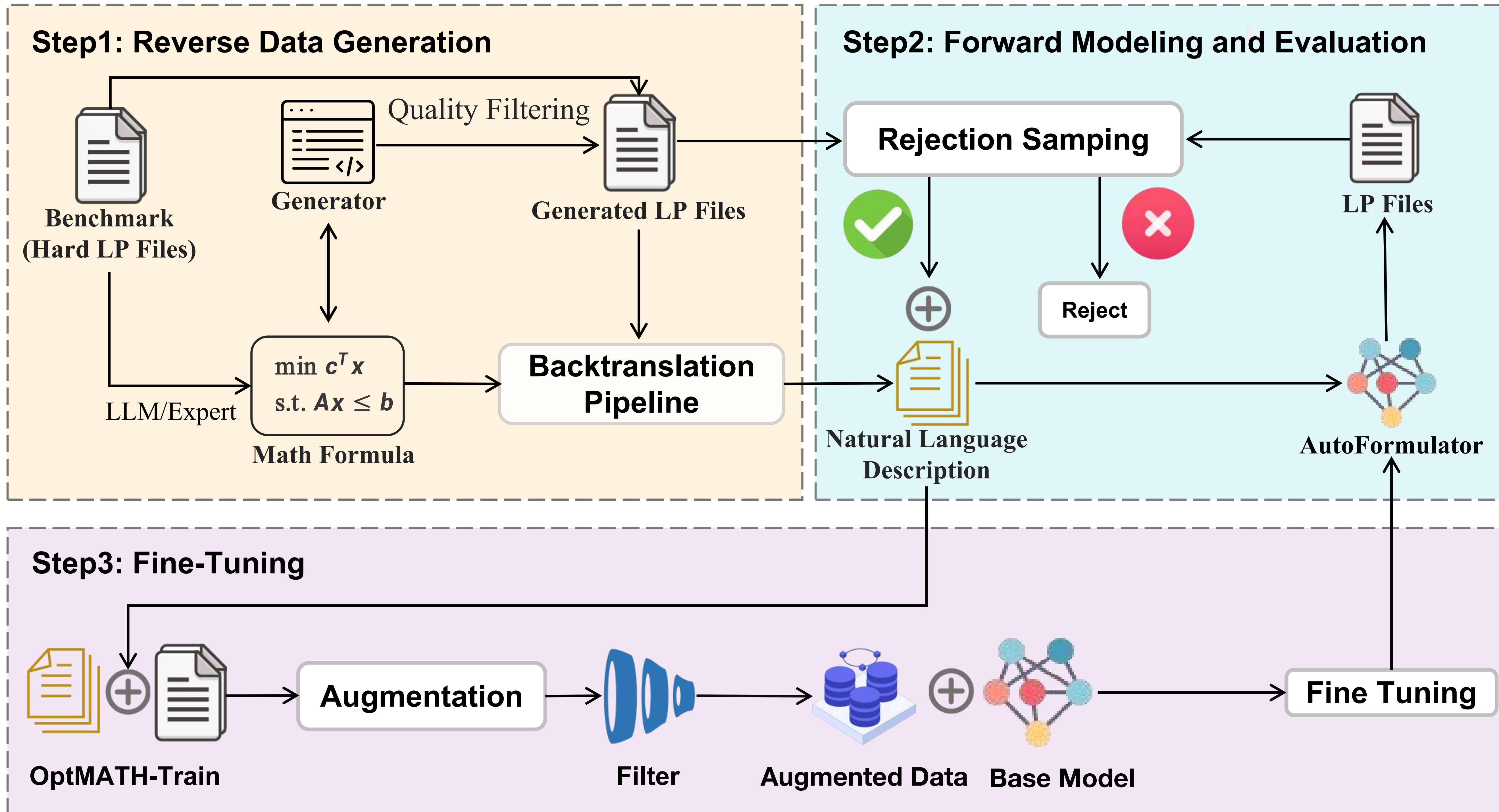


OptMATH: A Scalable Bidirectional Data Synthesis Framework for Optimization Modeling

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Dataset Statistics and Performance Results

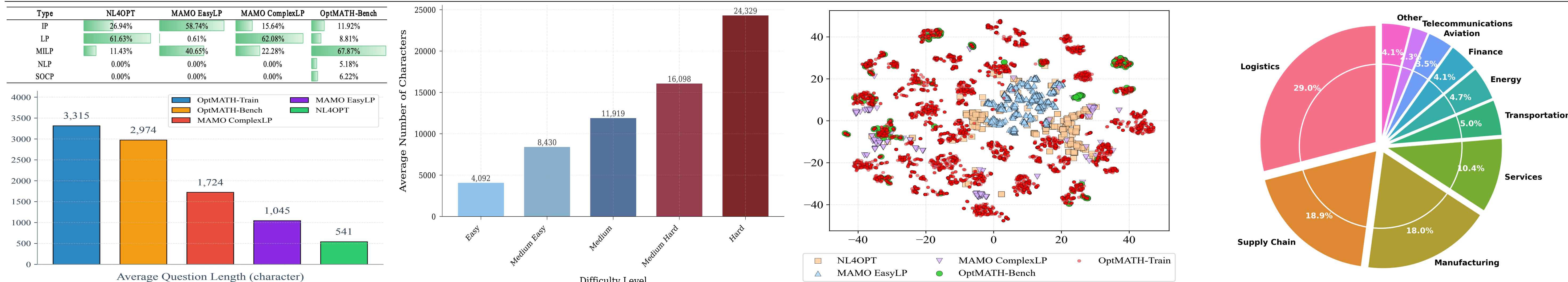


图 1. Problem type and length coverage

图 2. LP file length by difficulty

图 3. t-SNE visualization of problem space

图 4. Distribution of application scenarios

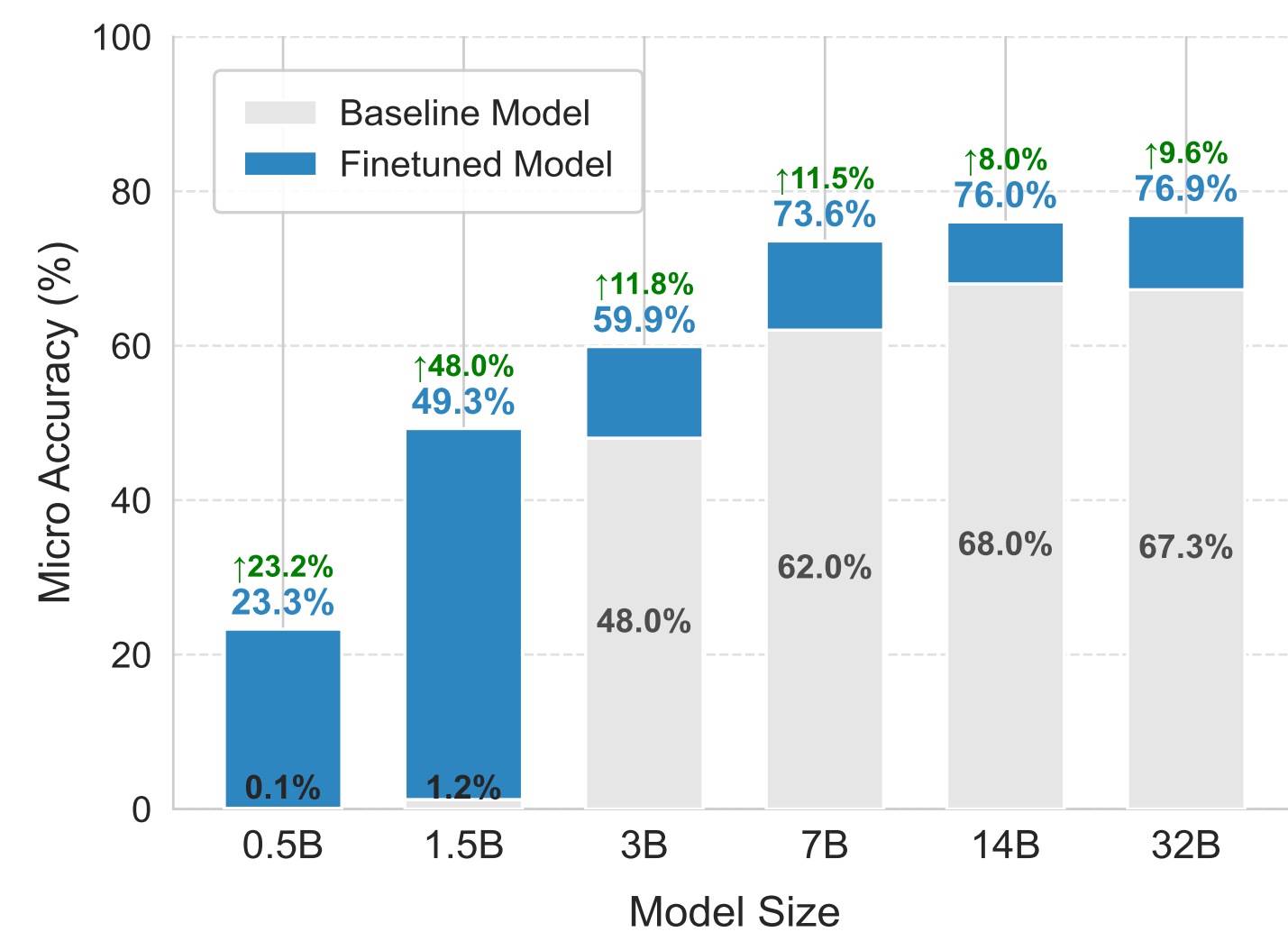


图 5. Model size scaling (0.5B-32B)

Types	Models	NL4OPT	MAMO EasyLP	MAMO ComplexLP	OptMATH Bench	IndustryOR	OptiBench	Macro AVG
Baseline	Llama3.1-8B	0.0%	0.2%	0.0%	0.0%	0.0%	0.0%	0.1%
	Qwen2.5-7B	86.9%	83.6%	21.8%	1.6%	10.0%	36.2%	40.0%
	GPT-3.5-turbo	78.0%	79.3%	33.2%	15.0%	21.0%	47.4%	51.4%
	GPT-4	89.0%	87.3%	49.3%	16.6%	33.3%	68.6%	57.4%
	Deepseek-V3	95.9%	88.3%	51.1%	32.6%	37.0%	71.6%	62.8%
Fine-tuning	OptiMUS (GPT-4o-2024-05-13)	78.8%	77.0%	43.6%	20.2%	31.0%	45.8%	49.4%
	Qwen2.5-32B	92.7%	82.2%	44.6%	9.3%	16.0%	47.6%	48.7%
	ORLM-Llama-3-8B (reported)	85.7%	82.3%	37.4%	*	38.0%	*	60.9%
	ORLM-Llama-3-8B (reproduced)	84.5%	74.9%	34.1%	2.6%	24.0%	51.1%	45.2%
	OptMATH-Llama3.1-8B (pass@1)	55.5%	73.9%	40.8%	24.4%	18.0%	55.5%	44.7%
Pass@8	OptMATH-Qwen2.5-7B (pass@1)	94.7%	86.5%	51.2%	24.4%	20.0%	57.9%	55.8%
	OptMATH-Qwen2.5-32B (pass@1)	95.9%	89.9%	54.1%	34.7%	31.0%	66.1%	62.0%
	OptMATH-Llama3.1-8B	97.6%	94.2%	71.6%	51.6%	37.0%	66.6%	69.8%
	OptMATH-Qwen2.5-7B	98.4%	94.5%	72.5%	56.0%	38.0%	68.1%	71.3%
	OptMATH-Qwen2.5-32B	97.9%	93.9%	75.4%	67.4%	47.0%	76.8%	76.4%

表 1. Performance Comparison of Models on Different Benchmarks

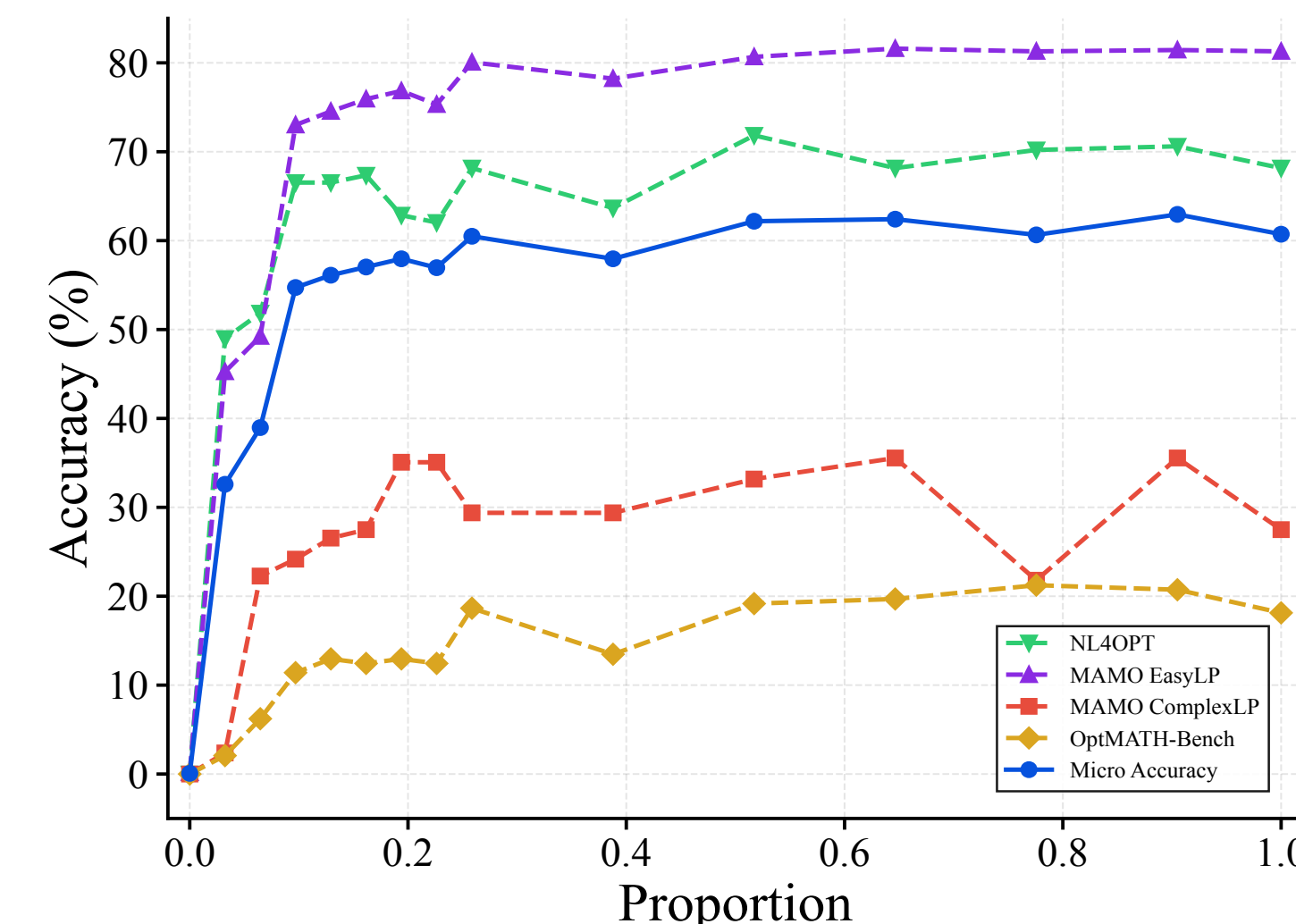


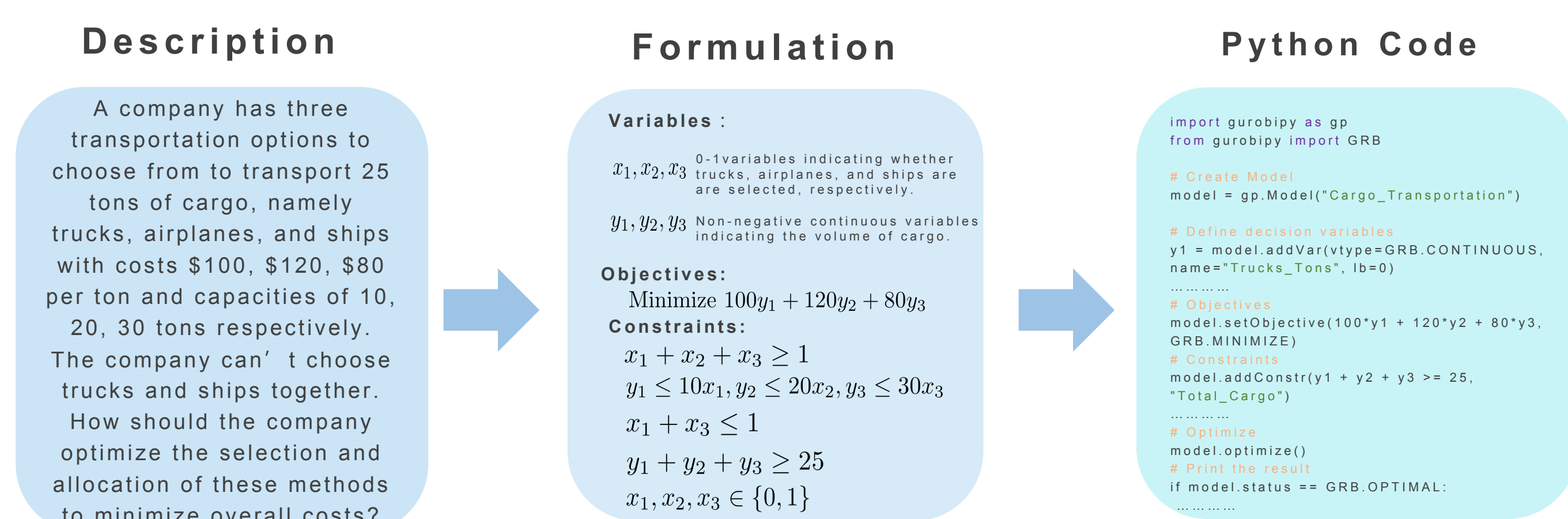
图 6. Training data scaling (Qwen2.5-1.5B)

Problem Formulation

The formulation for increasing the modeling capability of LLMs:

$$\begin{aligned} \max_{\theta} \quad & \mathbb{E}_{(NL, MF, PD) \sim \mathcal{D}} [Q_{(NL, MF, PD)}(MF', PD')] \\ \text{s.t.} \quad & (MF', PD') = \mathcal{A}_{\theta}(\text{prompt}_M(NL)) \end{aligned}$$

- \mathcal{A}_{θ} : Large Language Model with parameters θ
- Q : Quality metric for evaluation
- \mathcal{D} : Distribution of problem instances
- prompt_M : Modeling prompt template
- NL: Natural Language Description
- MF: Mathematical Formulation (abstract)
- PD: Problem Data (concrete, solver-ready)



Feedback-Driven PD Generation

Algorithm 1 Feedback-Driven Problem Data Generation

Require: Target complexity range $[S_{\min}, S_{\max}]$, time limits $[T_{\min}, T_{\max}]$, instance generator G , feasibility threshold $\mathcal{F}_{\text{target}}$, max iterations T

Ensure: Configuration Θ such that for $PD_i \sim G(\Theta)$: $S(PD_i) \in [S_{\min}, S_{\max}]$ (complexity), $\tau_i \leq T_{\max}$ (solving time), $\Pr(f_i = \text{feasible}) \geq \mathcal{F}_{\text{target}}$

- Initialize parameters via LLM:
 $\Theta_0 \leftarrow \mathcal{L}(\text{prompt}_{\text{IC}}(S_{\min}, S_{\max}, T_{\min}, T_{\max}))$
- for** $t = 1$ **to** T **do**
- Generate N PDs: $\{PD_i\}_{i=1}^N \leftarrow G(\Theta_{t-1})$
- Compute metrics: $S(PD_i)$ (Eq. 4), τ_i (solving time), f_i (feasibility)
- Aggregate statistics: $\bar{S}_t = \frac{1}{N} \sum S(PD_i)$, $\bar{\tau}_t = \frac{1}{N} \sum \tau_i$, $\mathcal{F}_t = \frac{1}{N} \sum \mathbb{I}(f_i = \text{feasible})$
- if** $\bar{S}_t \in [S_{\min}, S_{\max}]$ **and** $\bar{\tau}_t \leq T_{\max}$ **and** $\mathcal{F}_t \geq \mathcal{F}_{\text{target}}$ **then**
- return** Θ_{t-1}
- else**
- Refine parameters via feedback:
 $\Theta_t \leftarrow \mathcal{L}(\text{prompt}_{\text{RC}}(\bar{S}_t, \bar{\tau}_t, \mathcal{F}_t; \Theta_{t-1}))$
- end if**
- end for**
- return** \emptyset (no valid Θ found)

Complexity score function:

$$S(PD) = \alpha_{\text{bin}} N_{\text{bin}} + \alpha_{\text{int}} N_{\text{int}} + \alpha_{\text{cont}} N_{\text{cont}} + \beta_{\text{lin}} N_{\text{lin}} + \beta_{\text{indic}} N_{\text{indic}} + \beta_{\text{quad}} N_{\text{quad}} + \beta_{\text{gen}} N_{\text{gen}} + \gamma_{\text{BigM}} f_{\text{BigM}} + \delta_{\text{expr}} \overline{L_{\text{expr}}}$$

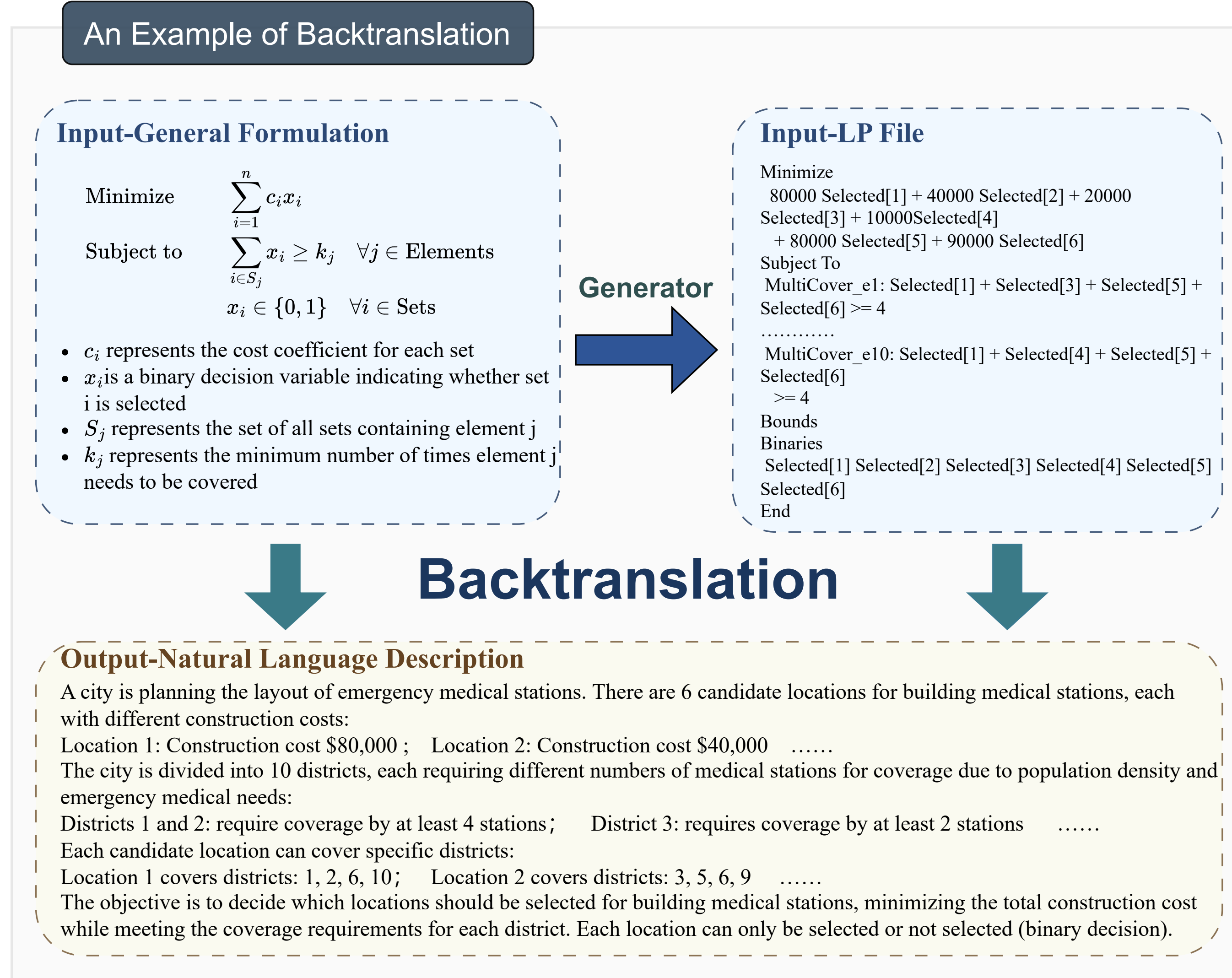
Bidirectional Data Synthesis Algorithm

Algorithm 2 Bidirectional Data Synthesis Algorithm

Require: Instance pair $(MF_i, PD_{i,j})$, Max Iteration T

Ensure: $(NL_{i,j}, MF'_{i,j}, PD'_{i,j}, OV_{i,j})$

- Initial generation: $NL \leftarrow \mathcal{L}(\text{prompt}_{\text{I}}(MF_i, PD_{i,j}))$
- Initialize: $SC = SR = \text{Null}$
- for** $k = 1, \dots, T - 1$ **do**
- Self-Criticize:
 $SC \leftarrow \mathcal{L}(\text{prompt}_{\text{C}}(MF_i, PD_{i,j}, NL))$
- Self-Refine:
 $SR \leftarrow \mathcal{L}(\text{prompt}_{\text{R}}(MF_i, PD_{i,j}, NL, SC, SR))$
- if** SR is good enough **then**
- break**
- end if**
- end for**
- $NL_{i,j} \leftarrow SR$
- AutoFormulation:
 $(MF'_{i,j}, PD'_{i,j}) \leftarrow \mathcal{A}_{\theta}(\text{prompt}_{\text{M}}(NL_{i,j}))$
- $OV_{i,j} \leftarrow \text{Solve } PD_{i,j} \text{ by Gurobi}$
- $OV'_{i,j} \leftarrow \text{Solve } PD'_{i,j} \text{ by Gurobi}$
- if** $OV_{i,j} = OV'_{i,j}$ **then**
- return** $(NL_{i,j}, MF'_{i,j}, PD'_{i,j}, OV_{i,j})$
- else**
- return** Null
- end if**



Training Strategy

Parameter-efficient fine-tuning with LoRA:

$$\mathcal{L}_{\text{SFT}}(\theta) = -\mathbb{E}_{(p,y) \sim \mathcal{D}_{\text{SFT}}} \left[\sum_{t=1}^{|y|} \log P_{\theta}(y_t | y_{<t}, p) \right]$$